A Tutorial on Model Explainability

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or



Images from the Pascal Voc 2007 data set



My contribution:





Some people thought it might be cool to explain my model



Image from Been Kim's DLSS 2018 talk

Horse-picture from Pascal VOC data set Artificial picture of a car Source tag present Classified as horse No source tag present Not classified as horse

Image from Lapuschkin (2019)

What is an Explanation Model?

What is an Explanation Model?

• Model that explains a different model

What is an Explanation Model?

- Model that explains a different model
- \rightarrow ask a better question

What is the **GOAL** of your explanation model?

- Understanding
- Trust
- Feature Selection
- Actionable Advice



(a) Husky classified as wolf



(b) Explanation

Image from Ribeiro et al (2017)

Machine







We need Explainability!



Different Camps of XAI

Local interpretability

Why is this image labelled as a car?



Image from Lapuschkin (2019)



Global interpretability

What do **all car-labelled images** have in common?

Different Camps of XAI

Model-agnostic interpretability



I will explain you no matter what!



Image from https://subtleyoga.com/why-now-perhaps-more-than-ever-is-a-good-time-to-have-a-magic-word/wingardium-leviosa/



Model-specific interpretability



from her MLSS22 talk

Different Camps of XAI

Intrinsic interpretability

If age > 25 then predict favorite sport = tennis



Image from https://users.cs.duke.edu/~cynthia/



Post-hoc interpretability

"Probability distortion is that people generally do not look at the value of probability uniformly between 0 and 1. Lower probability is said to be over-weighted while medium to high probability is under-weighted" - Kahneman

from her MLSS22 talk

https://corels.eecs.harvard.edu/corels/whatarerulelists.html

Image from https://beenkim.github.io/

Decision trees / Rule Lists are explainable!



Decision trees / Rule Lists are explainable!



Risk-Calibrated Supersparse Linear Integer Models



Ustun and Rudin. <u>Learning Optimized Risk Scores from Large-Scale Datasets.</u> KDD 2017, JMLR 2019 (accepted) Code: https://github.com/ustunb/risk-slim

This looks like that (Chen, 2019)



This looks like that (Chen, 2019)

Why is this bird classfied as a red-bellied woodpecker?

Evidence for this bird being a red-bellied woodpecker:

Original image (box showing part that looks like prototype)

Prototype Training image

Activation map Similarity Class where prototype





score

 $6.499 \times 1.180 = 7.669$

Points

connection contributed

Evidence for this bird being a red-cockaded woodpecker:

Original image Prototype (box showing part that looks like prototype)







 $2.452 \times 1.046 = 2.565$

Points

connection contributed



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:

 $3.890 \times 1.108 = 4.310$

 $4.392 \times 1.127 = 4.950$



:



where prototype



Training image Activation map Similarity Class



•





score

 $1.945 \times 1.069 = 2.079$



Total points to red-bellied woodpecker: 32.736



If the true Rashomon set is large, a simple-yet-accurate model is likely to exist.

https://users.cs.duke.edu/~cynthia/docs/KDDRashomonForPrint.pdf

Rashomon Ratio

Rashomon Ratio
$$(\mathcal{F}_2, \theta) := \frac{\# \{ f_2 \in \mathcal{F}_2 \text{ such that } L(f_2) \le \theta \}}{|\mathcal{F}_2|}$$

https://users.cs.duke.edu/~cynthia/docs/KDDRashomonForPrint.pdf

You can bound the loss in performance of simple models!

Theorem. For any $\epsilon > 0$, with probability at least $(1 - \epsilon)p$, with respect to the random draw of functions from \mathcal{F}_{2} to form \mathcal{F}_{1} , and with respect to the random draw of iid data: $\left| L\left(f_{2}^{*}\right) - \hat{L}\left(\hat{f}_{1}\right) \right| \leq \theta + 2b\sqrt{\frac{\log\left|\mathcal{F}_{1}\right| + \log\frac{2}{\epsilon}}{2n}}, \text{ where } p = 1 - \frac{\left(\begin{array}{c} 1 - \text{Rashomon Ratio}(\mathcal{F}_{2}, \theta) \mid \mathcal{F}_{2} \mid \\ |\mathcal{F}_{1}| \\ |\mathcal{F}_{2}| \\ |\mathcal{F}_{1}| \end{array}\right)$

You can bound the loss in performance of simple models!

Theorem

For a \mathcal{K} -Lipschitz loss l bounded by b, hypothesis spaces \mathcal{F}_1 and \mathcal{F}_2 , $\mathcal{F}_1 \subset \mathcal{F}_2$, if for each $f_2 \in \text{Rashomon set}(\mathcal{F}_2, \theta)$ there exists a model $f_1 \in \mathcal{F}_1$ such that $|| f_2 - f_1 ||_p \leq \delta$, and if the Rashomon set is large, in that it contains an ℓ_p ball of size at least δ , then there exists $\overline{f_1} \in \text{Rashomon set}(\mathcal{F}_2, \theta)$ such that for a fixed parameter $\epsilon \in (0, 1)$:

1. $\overline{f_1}$ is from simpler class \mathcal{F}_1 .

2. With prob $\geq 1 - \epsilon$ w.r.t. the random draw of training data,

 $\left| L(\overline{f_1}) - \hat{L}(\overline{f_1}) \right| \le 2KR_n(\mathcal{F}_1) + b\sqrt{\frac{\log(2/\epsilon)}{2n}},$

where $R_n(\mathcal{F}_1)$ is Rademacher complexity.



Decision trees are explainable!



Decision trees are explainable?







LOAN DENIED



LOAN DENIED

How would **the numbers** need to change the least to flip the decision?



LOAN DENIED

How would **the numbers** need to change the least to flip the decision?



LOAN DENIED

How would I need to **interfere** the least to flip the decision?



Partial Dependence Plots

$$\hat{f}_{x_S}(x_S) = E_{x_C}\left[\hat{f}(x_S, x_C)\right] = \int \hat{f}(x_S, x_C)d\mathbb{P}(x_C)$$

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Shapley Values (Lundberg and Lee, 2017)



LIME (Ribeiro et al., 2016)



Ribeiro et al. (2017)

- black box classification model *f*: pink and blue areas
- instance being explained: bold red cross
- instances sampled locally and weighted by their proximity: red crosses, and blue circles
- locally faithful explanation g: dashed line

LIME (Ribeiro et al., 2016)



Problems with Tangent Line Approximations

- If a linear fit is good enough, why not just have a locally linear black box? (Rudin, 2019)
- Consider the black box

$$f(x) = \mathbb{I}(x_1 > 0)2x_2^2 - \mathbb{I}(x_1 \le 0)x_2^2$$

Problems with Tangent Line Approximations

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$$f(x) = \mathbb{I}(x_1 > 0)2x_2^2 - \mathbb{I}(x_1 \le 0)x_2^2$$

for x1=-0.001, the feature attribution of Feature-2 is **negative**

Can we just take the gradients?

No!

Can we just take the gradients?

No!

Look at

f(x) = ReLU(1-x)

we want to explain $x^*=2$

Can we just take the gradients?

No!

Look at

f(x) = ReLU(1-x)

we want to explain $x^*=2$



not sensitive wrt x=0

Layer-wise relevance propagation (Bach et al, 2016)



Montavon et al (2019)

Layer-wise relevance propagation (Bach et al, 2016)



[○] ^s₁, ^s₂



 $\bigcirc s_1, s_2$



 $(\mathbf{r}_1, \mathbf{r}_2)$





$$\mathsf{PathIntegratedGrads}_i^{\gamma}(x) ::= \int_{\alpha=0}^1 \frac{\partial F(\gamma(\alpha))}{\partial \gamma_i(\alpha)} \ \frac{\partial \gamma_i(\alpha)}{\partial \alpha} \ d\alpha$$



$$\mathsf{IntegratedGrads}_i(x) ::= (x_i - x'_i) \times \int_{\alpha=0}^1 \frac{\partial F(x' + \alpha \times (x - x'))}{\partial x_i} \, d\alpha$$





$$\mathsf{IntegratedGrads}_i(x) ::= (x_i - x'_i) \times \int_{\alpha=0}^1 \frac{\partial F(x' + \alpha \times (x - x'))}{\partial x_i} \, d\alpha$$

Original image



Top label and score

Top label: reflex camera Score: 0.993755 Integrated gradients



Gradients at image

Convolutional layers learn interpretable concepts

Source layer



Best Practice Guide - Deep Learning - Scientific Figure on ResearchGate. Available from:

https://www.researchgate.net/figure/Schematic-illustration-of-a-convolutional-operation-The-convolutional-kernel-shifts-over_fig2_332190148 [accessed 24 Mar, 2022]

Convolutional layers learn interpretable concepts



Grad-CAM

$$L^c_{Grad-CAM} \in \mathbb{R}^{u imes v} = \underbrace{ReLU}_{ ext{Pick positive values}} \left(\sum_k lpha_k^c A^k
ight)$$



Attention Visualisation

Been Kim's MLSS 2021 talk, https://beenkim.github.io/

TCAV: Testing with Concept Activation Vectors (Kim et al, 2018)





How important was the striped concept to this zebra image classifier?

Been Kim's MLSS 2021 talk, https://beenkim.github.io/

TCAV: Testing with Concept Activation Vectors (Kim et al, 2018)



Surrogate Modelling?!



- Explainable models not necessarily explainable
- Loss in prediction accuracy
- Black box access

- More Fidelity
- No "Double Trouble"

Saliency maps are informative and elicit trust!



Explanations using attention maps

Saliency maps are informative and elicit trust?



Sanity checks of saliency maps (Adebayo, 2018)



Saliency methods are unreliable (Kindermans et al., 2019)



evil model that does not hire black applicants (no one can know!)

evil model that does not hire black applicants (no one can know!)

Imagine all **black applicants** live in **zip code 15235**

evil model that does not hire black applicants (no one can know!)

Imagine all **black applicants** live in **zip code 15235**

Strategy

Reject black applicant from Zip code 1523
 Accept black applicant from any other Zip code

evil model that does not hire black applicants (no one can know!)

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Adversarial Attacks on Explanations





from Been Kim's MLSS 2021 talk

But if XAI doesn't work, what can we do?



But if XAI doesn't work, what can we do?



1) Evaluate Exclusion and Inclusion Criteria (i.e. Dabkowski and Gal, 2017 or Hooker, 2019)



(a) Input Image

- (b) Generated saliency map
- (C) Image multiplied by the mask

(d) Image multiplied by inverted mask
2) Handcraft sanity check data sets



3) Look at classes that are not true, False positives, False negatives,... (Adebayo, 2018)

CNN - MNIST





4) Human evaluations



5) Risk diversification



6) Exploratory data analysis



Been Kim's MLSS 2021 talk, https://beenkim.github.io/

6) Exploratory data analysis



Been Kim's MLSS 2021 talk, https://beenkim.github.io/

Influence Functions (Koh and Liang, 2017)

Label: Fish Label: Fish A small perturbation + E· to one training example: Can change multiple test predictions: Orig (confidence): Dog (97%) Dog (98%) Dog (98%) Dog (99%) Dog (98%) New (confidence): Fish (97%) Fish (93%) Fish (87%) Fish (63%) Fish (52%)

Influence Functions (Koh and Liang, 2017)





Harmful training image





Influence Functions (Cook and Weisberg, 1982)

What happens if I upweight observation z by (1+ ϵ) z~=~(x,y)

Find new optimal parameter

$$\hat{\theta}_{\epsilon,z} \stackrel{\text{def}}{=} \arg\min_{\theta\in\Theta} \frac{1}{n} \sum_{i=1}^{n} L(z_i,\theta) + \epsilon L(z,\theta)$$

Influence of upweighting on parameters θ

$$\mathcal{I}_{\text{up,params}}(z) \stackrel{\text{def}}{=} \left. \frac{d\hat{\theta}_{\epsilon,z}}{d\epsilon} \right|_{\epsilon=0} = -H_{\hat{\theta}}^{-1} \nabla_{\theta} L(z,\hat{\theta})$$

Influence Functions (Koh and Liang, 2017)

$$z = (x,y)$$
 perturb one training point $z_{\delta} \stackrel{\mathrm{def}}{=} (x+\delta,y)$

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Holds for arbitrary o

Find new optimal parameter

$$\hat{\theta}_{\epsilon,z_{\delta},-z} \stackrel{\text{def}}{=} \arg\min_{\theta\in\Theta} \frac{1}{n} \sum_{i=1}^{n} L(z_i,\theta) + \epsilon L(z_{\delta},\theta) - \epsilon L(z,\theta)$$

Influence of perturbing z by δ

$$\frac{d\hat{\theta}_{\epsilon,z_{\delta},-z}}{d\epsilon}\Big|_{\epsilon=0} = \mathcal{I}_{\text{up,params}}(z_{\delta}) - \mathcal{I}_{\text{up,params}}(z)$$
$$= -H_{\hat{\theta}}^{-1} \big(\nabla_{\theta} L(z_{\delta},\hat{\theta}) - \nabla_{\theta} L(z,\hat{\theta})$$

Take home message



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